# New ways to design haptic interactions

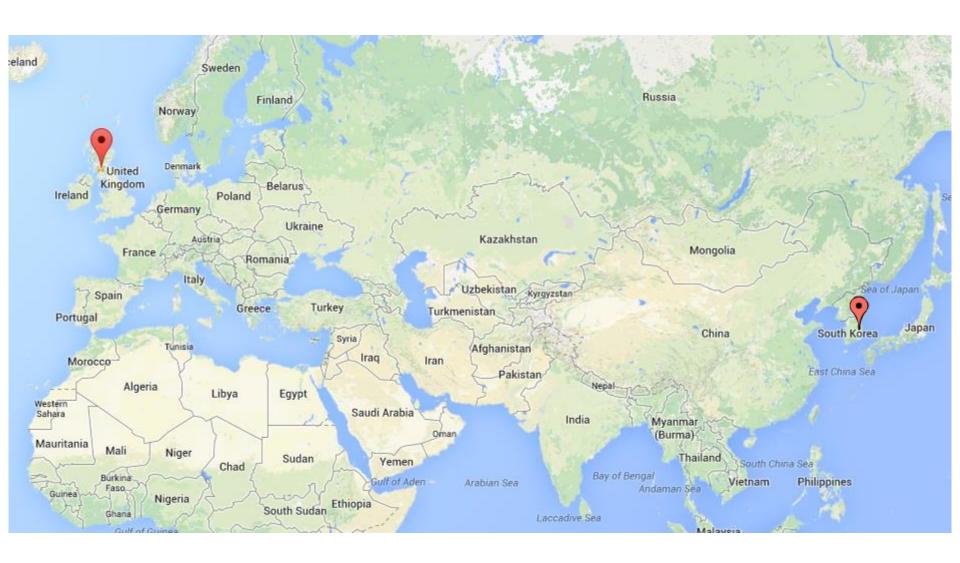




### Stephen Brewster

Glasgow Interactive Systems Group
School of Computing Science
University of Glasgow

stephen.brewster@glasgow.ac.uk





### Multimodal interaction

Key area of research is Multimodality

More human way to work

Not everyone has all senses / control capabilities

May not always be available all of the time

No one sense can do everything on its own

Using other senses/control capabilities to design new forms of interaction



### Research areas

Novel multimodal interaction techniques

Touchscreen and mobile user interfaces

Wearable devices

In-car interactions

Shared use of TV and phone/tablet

User interfaces for cameras

Accessibility

Blind users and visualisation, Older adults, navigation, mobility Multimodal home care

Mobile health apps



### **Modalities**

#### Non-speech audio

Earcons, 3D sound, sonification, Musicons

#### Computer haptics

Force-feedback, pressure input, temperature output

Tactile (vibrotactile and pin arrays), ultrasound

**Tactons** 

#### Gestural interaction

On-screen, with device, in-air

#### **Smell**



# What is haptics?

#### **Haptics**

Sense and/or motor activity based in the skin, muscles, joints and tendons

#### Two parts:

Kinaesthesia: Sense and motor activity based in the muscles, joints and tendons

Cutaneous/(touch): Sense based on receptors in the skin

ISO standard 9241-910 Tactile/Haptic interaction



#### Overview

Haptics has great potential but ...

Difficult to design good haptic interactions

Devices don't match human capabilities

How can we make better haptic interactions?

Need to think about it differently

Try different aspects of touch

Pressure input

Thermal output

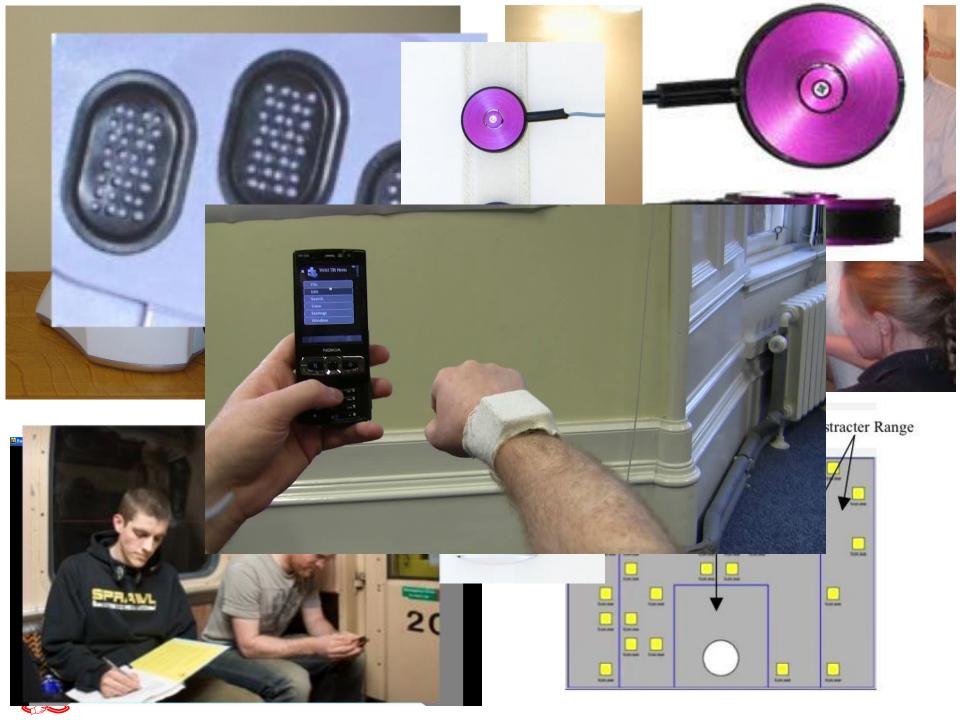


### Haptics

Over the years I have studied haptic interaction in many different settings with many different devices

Many different frustrations ...





# But there are always problems

#### Devices have significant limitations

Hardware

Software

Mismatch between human capabilities and devices

#### Hard to create 'real' experiences

Force feedback devices always feel spongy, hard to do torque forces

Vibrotactile devices just feel like .... vibrotactile devices



### Solutions?

Use aspects of touch for which we have good sensing or actuation

Pressure input

Thermal feedback

Rich human experiences

Hardware/software available now

Little research to guide design



### **PRESSURE**

### Pressure input

Little studied in HCI, but a rich source of input and control

Musical instruments

Drawing (graphics tablet), holding / grasping

Can we uses pressure as another input mechanism?

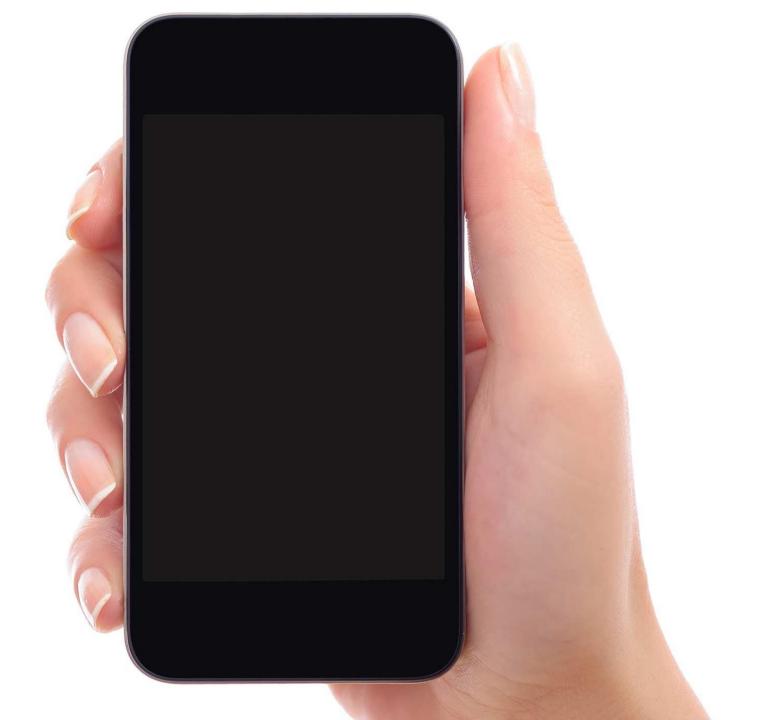
No need for spatial positioning of finger

Easy to do 'eyes free'

Can use the z-axis

Does not require change of grip, allows interaction while gripping







#### Pressure

Pressure sensing does not require manipulation of angle of the device

Unlike accelerometers or gyroscopes for tilt control

Pressure can be distributed over a large area meaning it can be accessed using multiple postures



### Hardware

Many types

We use force sensing resistors

Thin

Flexible

Cheap





# First attempt: Pressure input

Pressure keyboard on standard Nokia N800

Light press = lower case,

Hard press = upper case

Good for entering mixed case text, punctuation, emoticons, function keys, ...

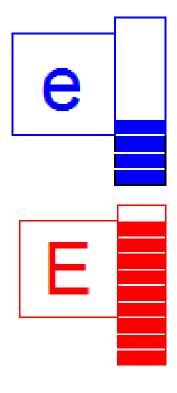


Dynamic feedback

Tested users sitting and walking

Pressure can be as fast as regular keyboard

Lower error rate, especially when mobile



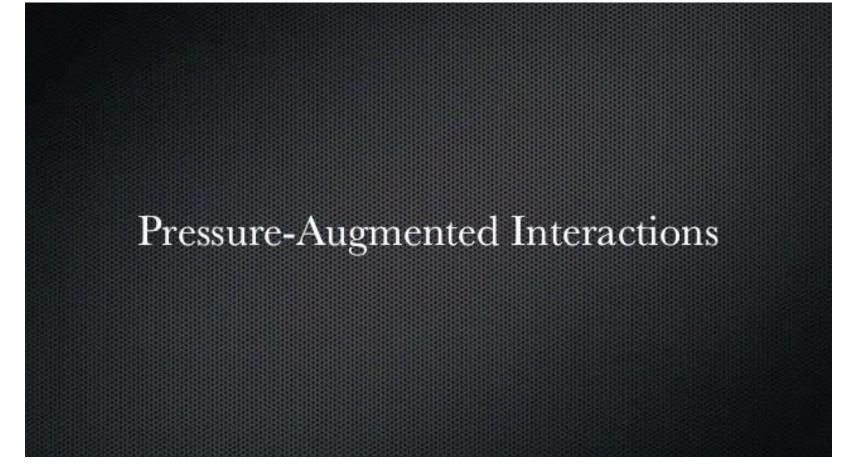


# Pressure keyboard





# Other pressure interactions





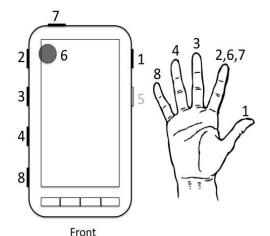
# Grip and grasp

Can we use the way we grip a device to control it?

Can we use this for interaction?

Make a two-handed interaction into a one handed version















# Grip results

Compared rotate and zoom

Pinch/rotate using multitouch and 2 hands

Grip

One handed grip equal to or better than traditional method

No finger occlusions

Works well for non-visual input as fingers don't need to move

Also works well when walking

Squeezing devices very effective for input



# Pressure for two-handed input

Pressure can be used in other situations

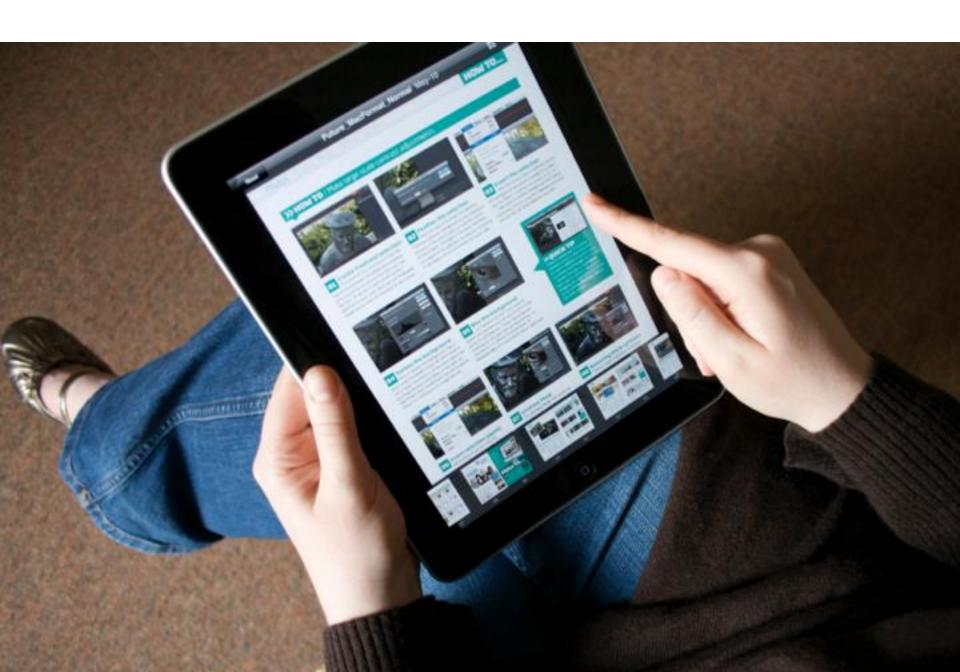
Phone or tablet

Non-dominant hand supporting device

Cannot move

But could provide pressure input





# Pressure and dial input

Separated scrolling speed from scrolling direction

Direction was dominant hand (DH)

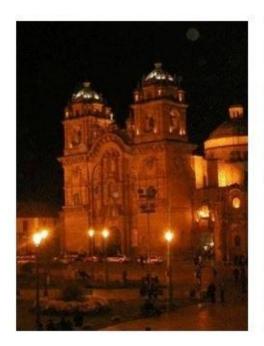
Speed was non-dominant hand (NDH)

Accelerator





















### Results

Pressure was successful

Users could control it well while using the dial

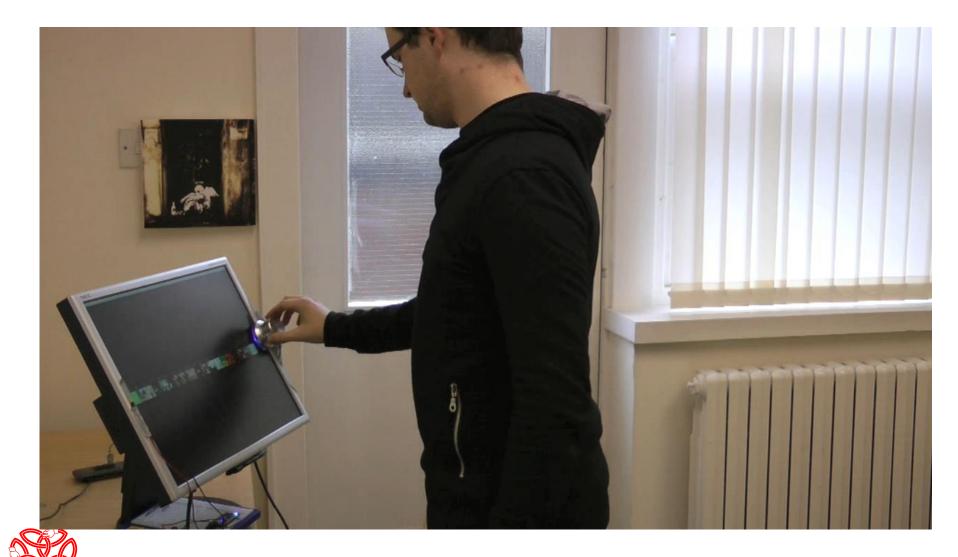
Accelerator model worked well

Easy to make small movements

Pressure to increase scrolling speed – very natural



# FineTuner



# Problems with pressure

Selection is always difficult using pressure

**Quick Release** 

Dwell

QR

Difficult to detect reliably

Dwell

Slows interaction down



Selection event often does feel natural

### Pressure input is transient

#### Natural Inverse

intrinsic inverse action that produces an opposite effect

#### Bounce-Back

returns to its initial state soon after the user has relinquished control



Transient

natural inverse occurs automatically whenever control is released



### Transient pressure

Can users operate pressure input without having a negative effect on dominant hand interactions?

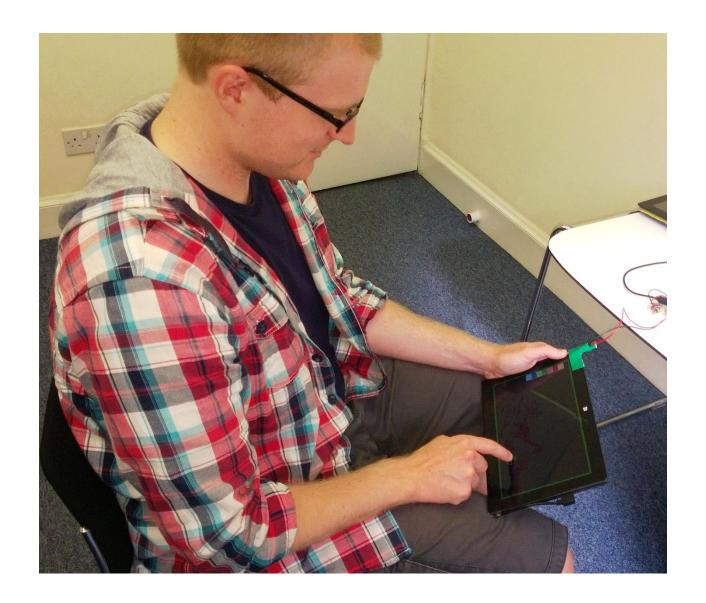
#### **Targeting**

How accurately can users a provide two-handed combination of pressure and touch input

#### Maintaining

How accurately can users maintain different levels of pressure during a bimanual interaction







# Transient and Transitional States Pressure as an Auxiliary Input Modality for Bimanual Interaction



# Targeting study

Single crosshair appeared on the screen, the colour of which signified the item to select in pressure menu

Navigate to the corresponding colour in the pressure menu (NDH) while tapping the crosshair (DH)

#### **Tested**

Menu size, target distance

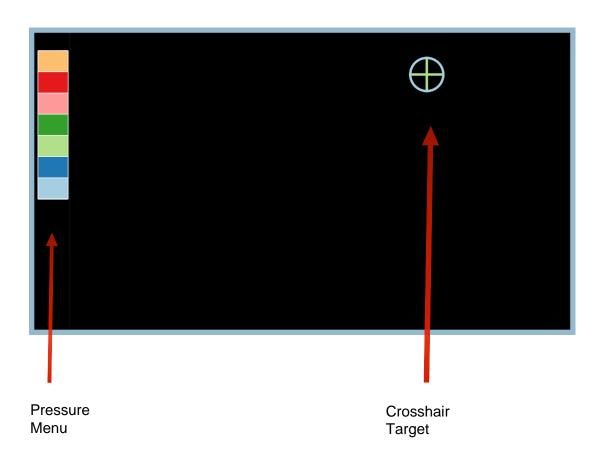
#### Measures

Time

Non-Dominant Hand (NDH) accuracy

Dominant Hand (DH) accuracy







### Results

Menu Size	Selection Time (ms)	Pressure Accuracy	DH Error Distance (px)
Control (0 items)	649.85	n/a	21.8
5 Items (W= 2N)	2334	93.6%	27.5
7 Items (W= 1.4N)	2520.2	96.1%	18.8
10 Items (W = 1N)	2889.5	89.3%	25.3

Pressure very successful – accuracy for both hands was high as time increased



## Maintaining

Navigate to a particular level of pressure and maintain that level as accurately as possible while selecting DH targets

#### **Tested**

Target pressure (2,4,6,8N)

Maintain time (5,10,1,20s)

#### Measures

Pressure variance

Pressure error



### Results

Target Pressure	Mean Pressure Variance (N)	Mean Pressure Error (N)
2N	0.648	0.157
4N	0.349	0.162
6N	0.292	0.135
8N	0.104	0.096

People very good at maintaining pressure while selecting



### Overall results

Low impact on dominant hand accuracy

Pressure accuracy high across all conditions

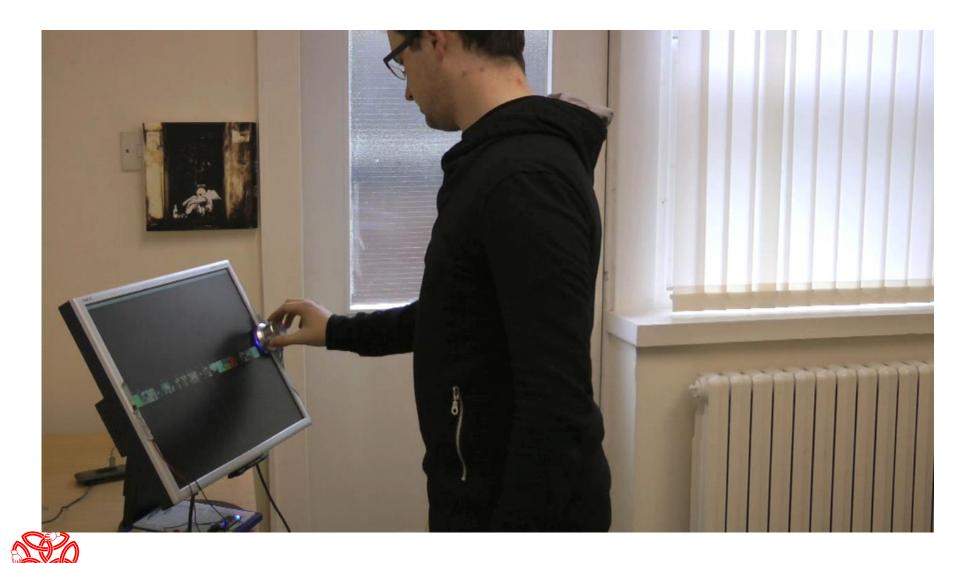
Accurately select targets by both applying and releasing pressure

Maintain pressure more accurately as the target pressure increases

✓ Non-dominant hand pressure works very well



# FineTuner



#### THERMAL FEEDBACK

### Thermal interaction

Temperature an unused part of touch feedback

It is always present

Humans are very sensitive to temperature

Can we use it for communication?

Very strong emotional response to temperature Key technique for determining material properties Children's hotter/colder game



Alternative to a vibration motor?

# Thermal feedback

Vibration motors don't give a convincing feeling of any material

Their ability to produce stimuli is much less than human perception capabilities

Engineering challenges make this difficult to fix

Thermal devices stimulate the skin in a convincing way

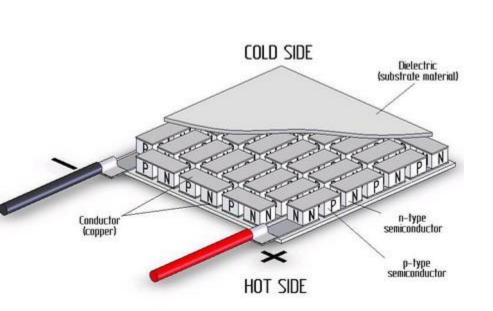
Same as occurs when touching warm or cool objects Feeling is therefore much more realistic

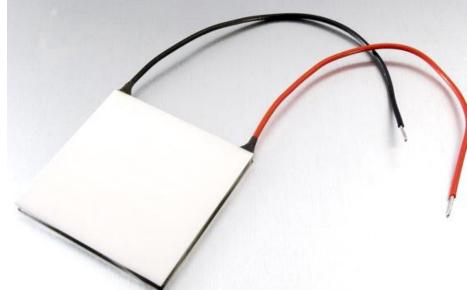


# Temperature hardware

#### Peltier heat pumps

Elements that can be heated or cooled rapidly Standard components, low cost





# Thermal feedback device

We built a thermal feedback device

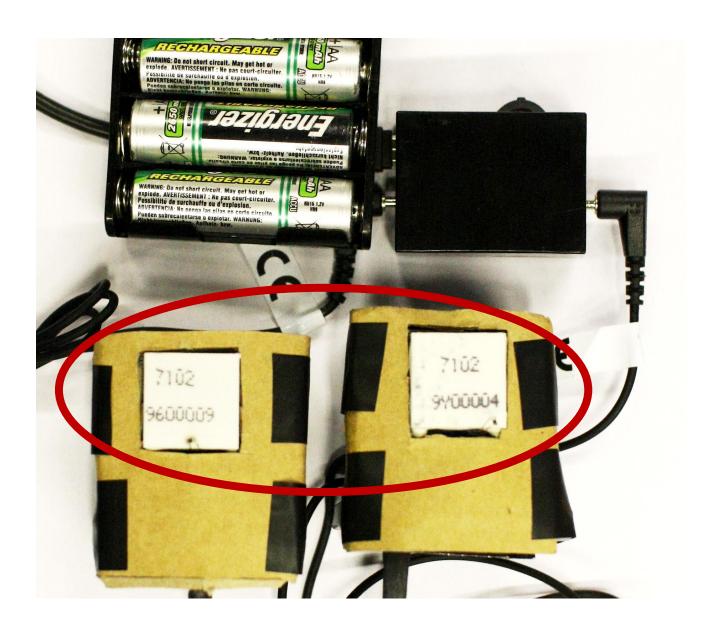
Has 2-4 Peltier elements

Battery powered

Communicates via Bluetooth

Power consumption similar to video playback for our thermal cues







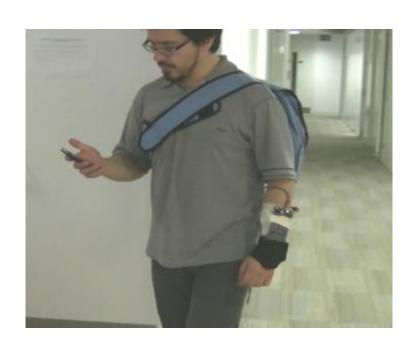
### Studies

Investigated perception of thermal stimuli in many different ways

- **Body location**
- Amount of change required
- Rate of change
- Static vs mobile use
- Through clothes vs bare skin
- In varying indoor and outdoor environments



# Indoor mobile thermal study

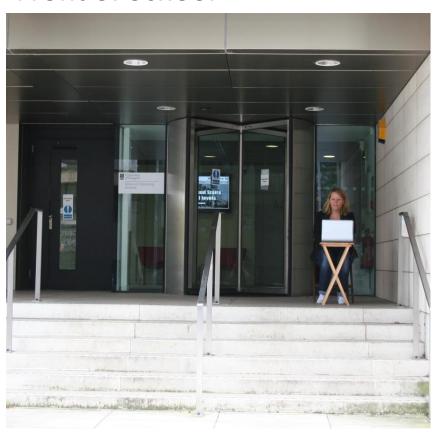






# Effects of changing environment

#### **Front of School**



**Back of School** 



### Design Recommendations

Palm is most sensitive but wrist and arm are acceptable Stimulus intensities should be at least 3°C to guarantee detection but 6°C at most for cooling and <6°C for warming to ensure comfort

Both warm and cool stimuli are detectable and comfortable but cool stimuli are preferred

Cool detected fastest

Moderate rate of change (2-3°C/sec) provide good saliency but lower rate of change required for high intensity stimuli

Users' affective response very strong



# **Applications**

Thermal icons

Notifications and warnings

Multimodal combination with vibrotactile to increase range of non-visual display options

#### Enhancing emotional experiences

Thermal feedback can enhance the experience of consuming media (images, music)



### Conclusions

Haptic interaction can be problematic as devices don't match the capabilities of the human

Creates experiences that do no feel 'real' or engaging

Need to design better haptic interactions

Use aspects of touch for which we have good devices

#### Pressure input

Rich form of control

Users can control it well with both hands

Hardware simple to add to mobile devices, other products



### Conclusions

#### Thermal feedback

- Rich part of human touch experience
- Creates a more emotional link
- Don't need large changes in temperature to elicit responses

#### New ways to design haptic interactions

If we create new interactions like this then user experiences will be much richer and more engaging than what is available now



# New ways to design haptic interactions





### Stephen Brewster

Glasgow Interactive Systems Group
School of Computing Science
University of Glasgow

stephen.brewster@glasgow.ac.uk